

## Virtual Test Driving and Digital Twins: Accelerating the Shift to Software-Defined Vehicles

Tampere Automotive & Vehicle Technology Cluster's International Networking Event

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Carl Squire - Managing Director, IPG Automotive USA, Inc.

David Howarth - Director, Global Software Strategy

Ben Duprey - Product Owner, Vehicle Dynamics and Modeling

# Ben Duprey – Simulation Technical Specialist | Product Owner, Vehicle Dynamics and Modeling

#### **Organizations**

- IPG Automotive, Inc. (2022 present)
- Mechanical Simulation Corporation (2010 2021)
- Continental Corporation (2004 2006)
- Honda R&D Americas, Inc. (2003)
- Saleen, Inc. (2001)

#### **Professional Society Activity**

- SAE (20+ years)
- ComVec (2008 present)
- Vehicle Dynamics Standards Committee (2011 present; Currently serving as Chair)
- Associate Editor, Journal of Commercial Vehicles (2016 present)
- Truck & Bus Vehicle Dynamics Modeling and Simulation Task Force (2023 present)

#### **Education**

- Virginia Tech MS (2006 2009)
  - Thesis "A New Fuzzy Logic Based Stability Index Using Predictive Vehicle Modeling and GPS Data."
- RIT BS, Mechanical Engineering (1999 2004)
  - FSAE Continental Best-in-Class Brake System Award (2004)

#### **Publications (SAE)**

- ComVec 4 technical papers
- Guest Editor Fundamentals of Vehicle Dynamics, Revised Edition

#### **Publications (non-SAE)**

 Manuscript Review - Algorithms for Decision Making (Mykel J. Kochenderfer, Ph.D., MIT Press, 2022)

#### **Research Interests / Activities**

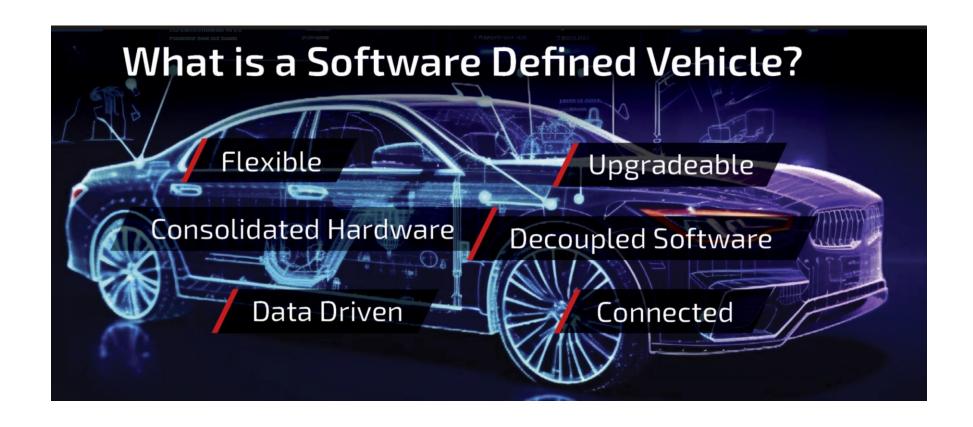
- Fuzzy Logic
- Game Theory
- Decision Making Under Uncertainty



## **Presentation Outline**

- Software-defined Vehicles, Virtual ECUs, and Shift-left topics
- Application Rapid Software Validation
- IPG CarMaker and the Virtual Vehicle Prototype

## **Software-Defined Vehicles (SDV)**





## **Software-Defined Vehicles (SDV)**

### What is an SDV?

- A car whose primary functions and features are managed and enhanced through software.
- OTA Allows for updates, new features, and customization.
- Features No longer tied to fixed hardware.

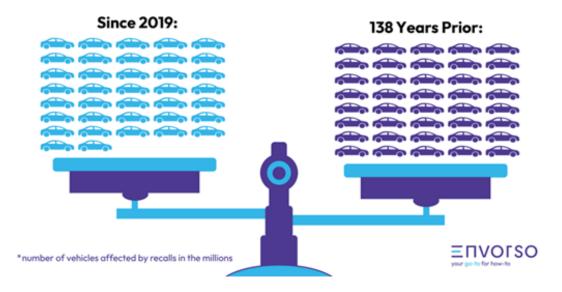
## Software, rather than hardware, is the driver for functions and connectivity

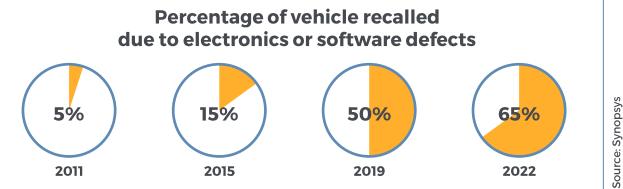
- Software-defined Development
- Upgradeable over time
- Modern software architectures and cloud-based services
  - Vehicle Both a sender and receiver of data

## **Software Warranty Costs are Crushing the Industry**



#### The Software Recall Epidemic in Vehicles





Source: ENVORSO

## **Key Factors Driving the Issue**

## Software and system complexity are growing rapidly

(ADAS, SDV, HMI, electrification, etc.)

## Traditional testing - Too much time to find and fix bugs quickly



Vehicle System HILs Complex, expensive, not scalable



Track Testing
Time-consuming, expensive,
limited scope



Test Coverage
Lack of scenario testing and vehicle
correlation throughout process



Result - Significant defects make it to production

**9**IPG

## Silicon Valley Innovation: Workflow!



Silicon Valley software companies (e.g. Google, Amazon) solved a similar challenge 15 years ago

- Complexity drove a reduction in software quality & reliability
- Important lesson Workflow concept of Rapid Software Validation
  - Software changes from <u>all</u> developers integrated together and tested in hours
  - Bugs are found while software changes are still fresh in developers' minds
     ... enables rapid rework
- Discussions frequently involve the idea "it's cheaper to find bugs earlier than later"
  - While helpful (8 weeks reduced to 2 weeks), it does not fully solve the problem
     ... Use the Silicon Valley mindset instead ...

"Test It before You Forget It"

Test all S/W changes together in hours to yield significant improvements in S/W quality

## **Use Silicon Valley Innovation to Improve Auto S/W Quality**

#### **WORKFLOW**

vECU on SIL

**Rapid HIL** 

VIL V&V

**IPG Automotive** has developed **rapid validation** workflows to apply these principles to **existing** controls-based software development

- Three Stages integrated into one CI/CD workflow
- Rapid cycle time (hours for each stage)
- Extensive test coverage

#### VIRTUAL VEHICLE PROTOTYPE

Using the CarMaker virtual vehicle prototype in each stage simplifies test setup and execution

- Integrate all dependent electronic controls
  - Built-in RestBus simulation
- Correlate vehicle test results at every stage
  - Prove simulation matches physical testing

### **Focus - Automated S/W V&V Testing**

#### **RAPID SOFTWARE VALIDATION STRATEGIC STAGES**







vECU on SIL

Rapid HIL

VIL V&V

### ... not S/W Development Applications



MIL



Component & Sub-System HILs



Driving Simulators

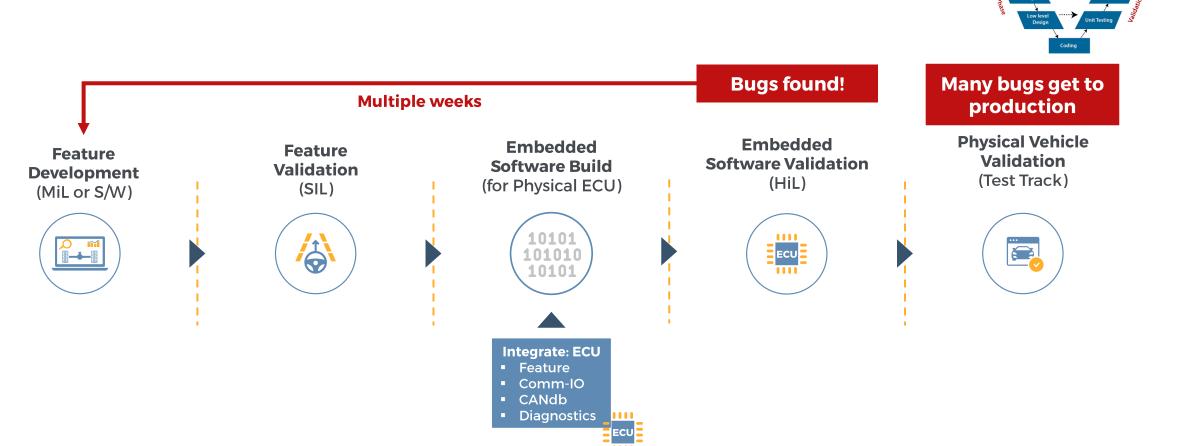


**Test Beds** 



VIL

## "As Is" Automotive Approach



Prolonged Loop Time: Tempo of code changes outpaces ability of these test systems to debug Vehicle System HIL Complexity: Unrealistic to add new HIL systems given cost and complexity

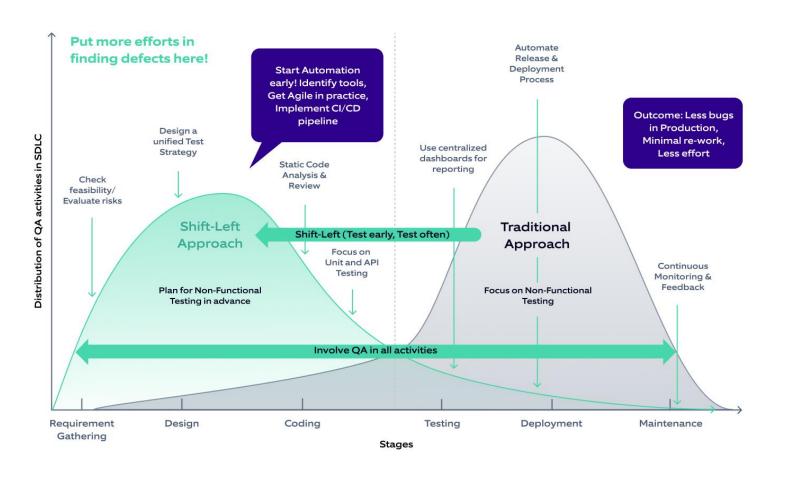


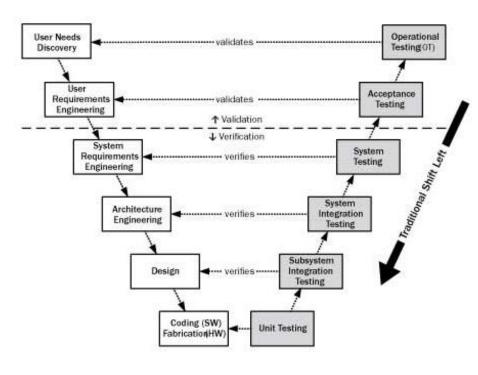
V- Model

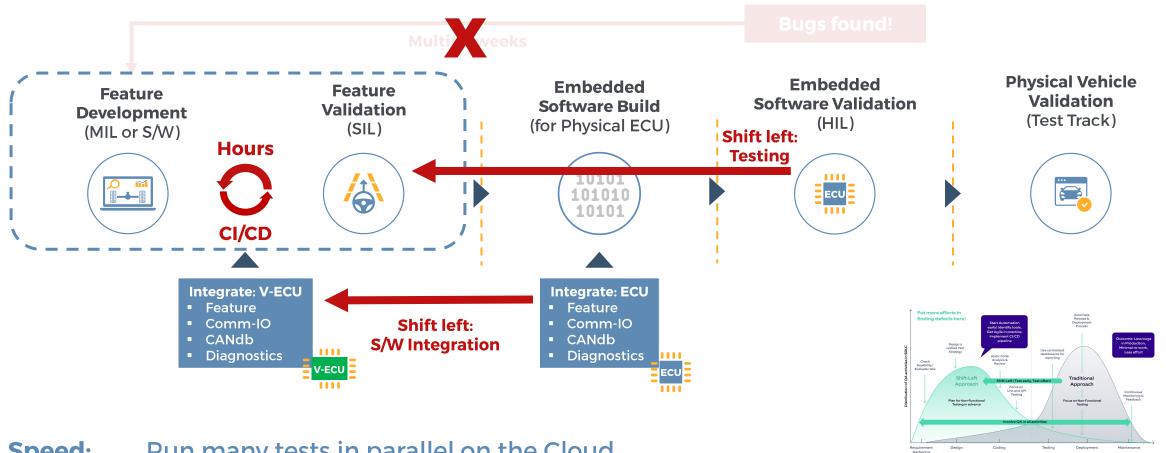
Tester's Life Cycle

Developer's life Cycle

## Test early and Test often - "Shift left"





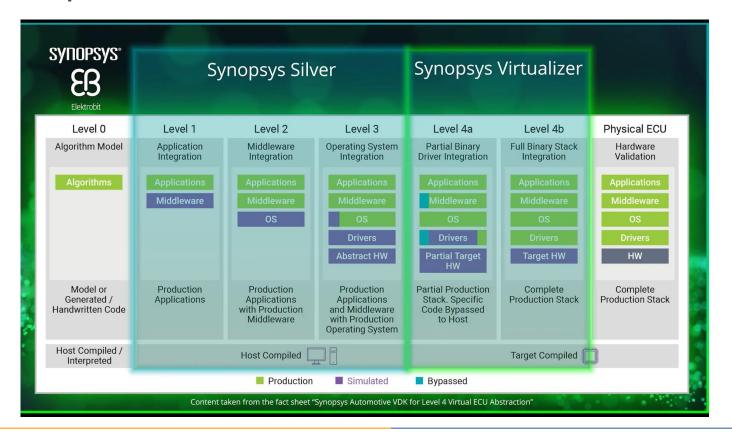


Speed: Run many tests in parallel on the Cloud

Scenario tests, message tests, static code tests, diagnostic tests, fault-insertion

## Virtual Prototyping using Virtual ECUs

- Ensure accurate ECU behavior in virtual environments
  - Levels 1 3 Software-in-the-Loop (SIL): Run software on your host
  - Level 4 Representation of virtual hardware





# Rapid Migration of Existing Workflows: vECU on SIL

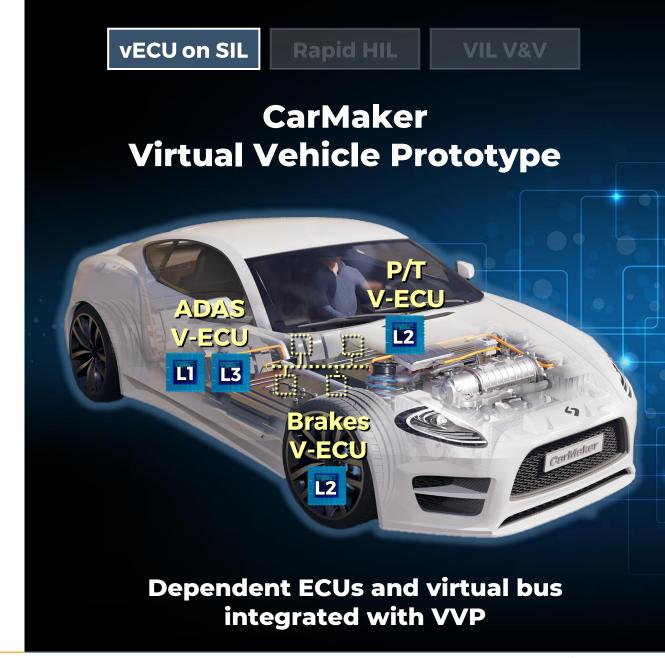
Use two different vECUs to achieve both **Speed** and **Coverage** for "layered integration" testing

#### **Speed: Level-1 vECU for fast testing of many scenarios**

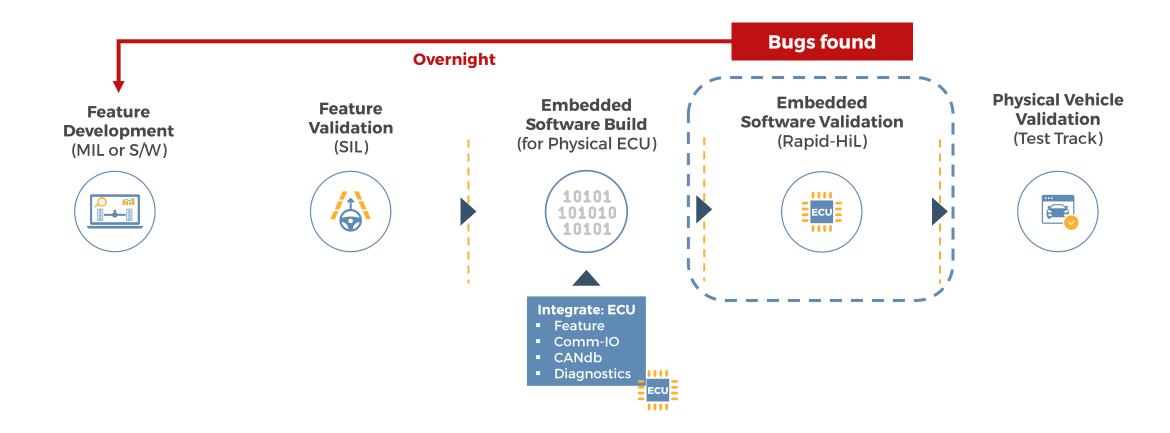
- Test function behavior for feature developers
- Simplicity and scalability (FMU "signals")
- Fast completion of significant quantity of scenariobased tests on the cloud

#### **Coverage: Level-3 vECU for "layered" integration testing**

- Test Production-Intent integration of:
   Feature + Base Software + CANdB + diagnostics
- Test Vehicle System integration of:
   vECU (SUT) + dependent vECUs on virtual CAN bus
- Test bus messages and scenarios



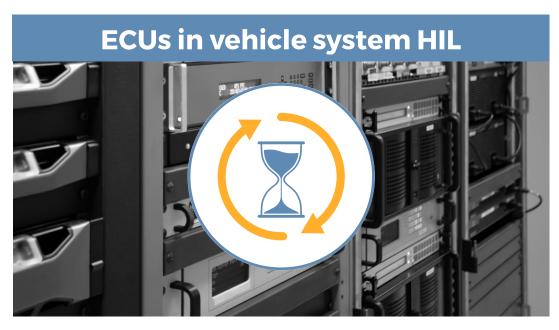




Speed: Massively increase throughput using scalable, low-cost Rapid-HIL farm

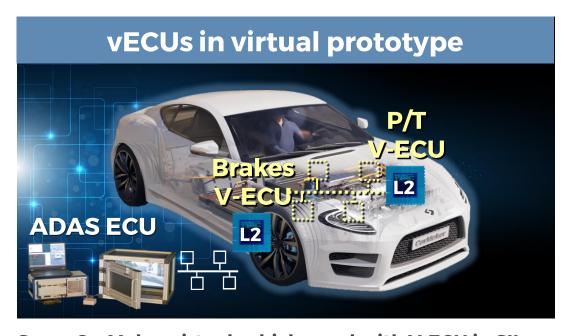
Coverage: Scenario tests, Message tests, Static code tests, Diagnostic tests, Fault-insertion





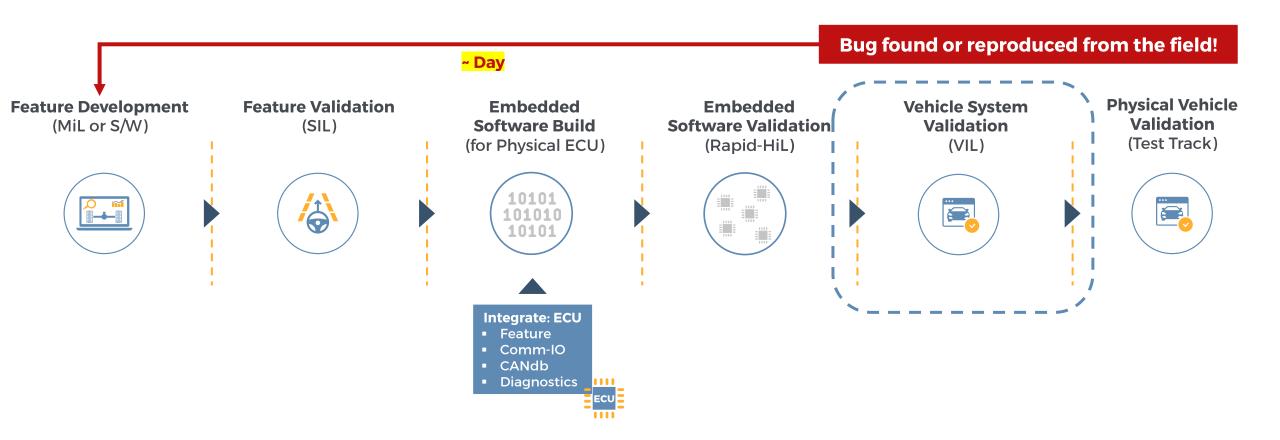
#### **Challenge of current Vehicle System HILs**

- Vehicle physical ECUs connected on big "bread-board"
- ECU software version management at test bench
  - Restbus managed at the bench
  - Restbus and ECU network issues result in debugging on the bench, reducing uptime



#### Same CarMaker virtual vehicle used with V-ECU in SIL

- Dependent ECUs virtualized and connected in virtual vehicle
- ECU version management in virtual vehicle, not bench
  - Restbus managed in virtual vehicle
  - Find bus errors at build time, not later at the bench



**Speed:** Include VIL in CI/CD automation to generate results in one shift

Coverage: Correlate real-world results with virtual vehicle from simulation (SIL/HIL)

# Rapid Migration of Existing Workflows: VIL Validation

#### Virtualization and production correlation

- Correlate the physical results from VIL with the simulation results from SIL and Rapid HIL
  - Prove the simulations can be trusted
  - Run a set of the same scenarios in each of the workflow stages for correlation



## **Accelerating SDV Dev. with Virtual ECUs**

#### Enable Shift-left

- Test early and test often
- o Rapidly identify issues while they are still fresh in the developers' minds
- Leverage SIL and Rapid Software Validation workflows

### Virtual ECU

- Shift from HIL to SIL
- Run with AUTOSAR Classic software
- Rapid software updates as part of CI / CD workflows

## **Summary**

#### **Main lesson from Silicon Valley re: Software Quality**

- Validation results Generated in hours
- Accessibility ALL developers

#### **Workflow - Three Stages in one CI/CD process**

- 1. Shift left with vECUs
- 2. Rapid HIL farm
- 3. VIL for software validation

#### The CarMaker virtual vehicle prototype

- All dependent ECUs integrated and connected together via the Virtual Vehicle Prototype
- 2. Correlate virtual test results with physical test results
- 3. Part of a larger eco-system with Partners

#### **Achievable today**

Biggest challenge: Organizational change

